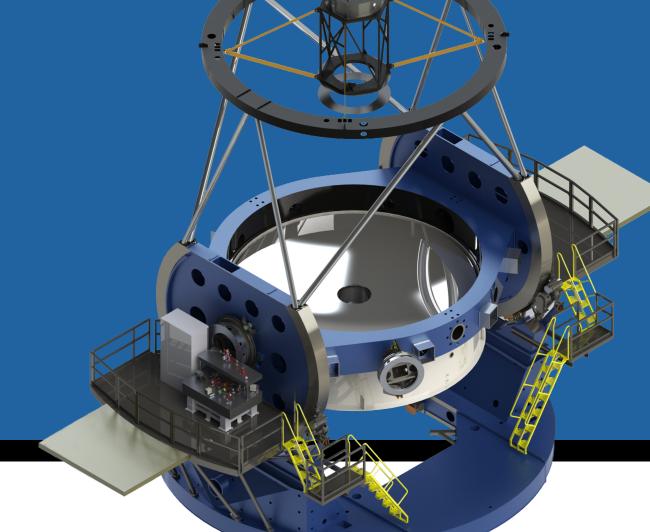


### **Characterization of Deformable Mirrors for the MagAO-X Project** *Kyle Van Gorkom<sup>1</sup>, Kelsey Miller<sup>1</sup>, Jared Males<sup>2</sup>, Olivier Guyon<sup>1,2,3</sup>, Alexander Rodack<sup>1</sup>, Jennifer Lumbres<sup>1</sup>, Justin Knight<sup>1</sup>* <sup>1</sup>College of Optical Sciences, University of Arizona, <sup>2</sup>Steward Observatory, University of Arizona,

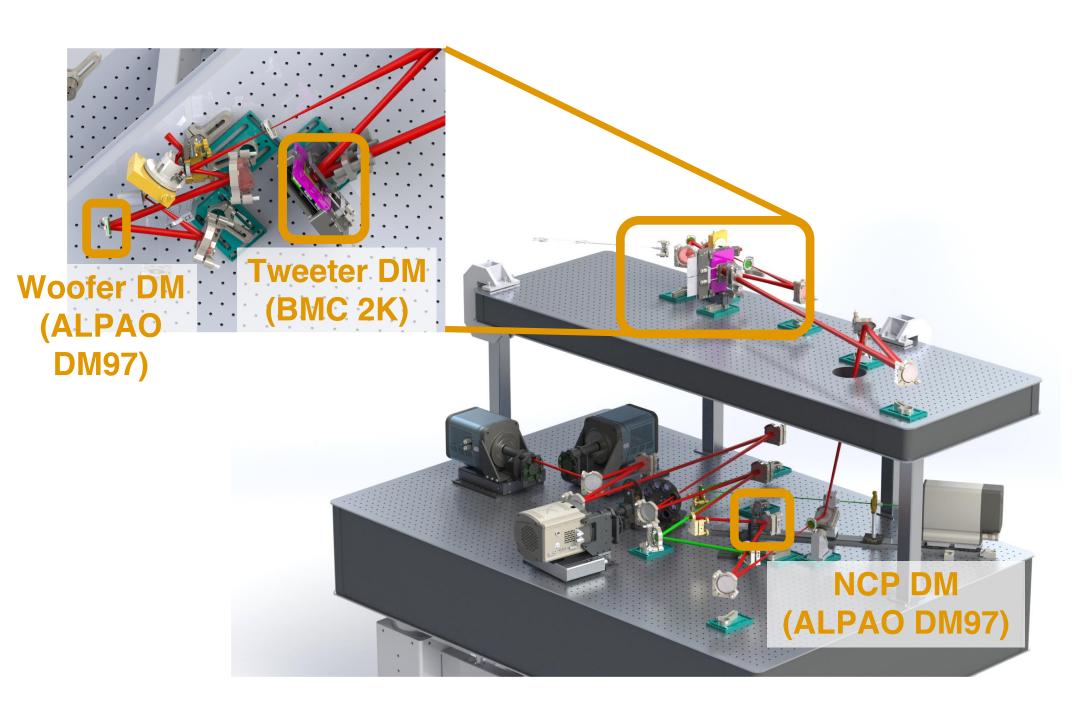
<sup>3</sup>Subaru Telescope, National Astronomical Observatory of Japan

actuator pitch

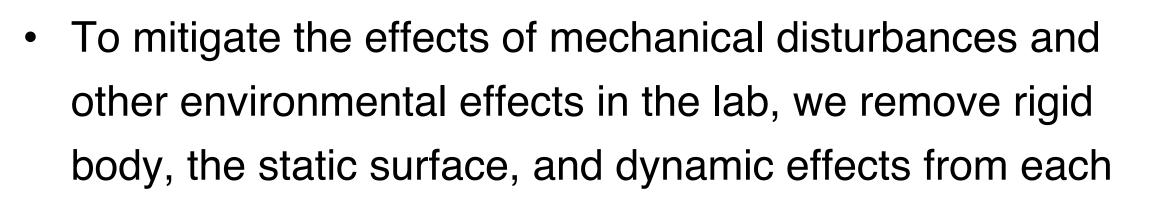
height



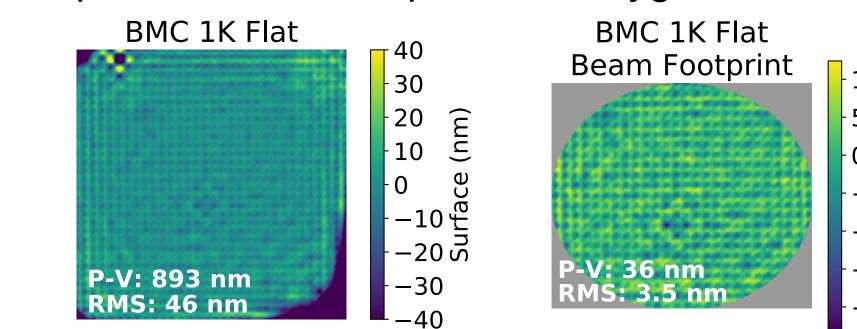
### Introduction



 The influence function (IF) is the response of the DM surface to a singleactuator stroke. We construct a general shape on the DM through a linear combination of all actuator influence functions.



With a BMC 1K (32x32) currently in use in the UA lab, we have demonstrated the ability to drive a BMC DM to a powered flat of 3.5nm RMS over our beam footprint in closed loop with the Zygo.

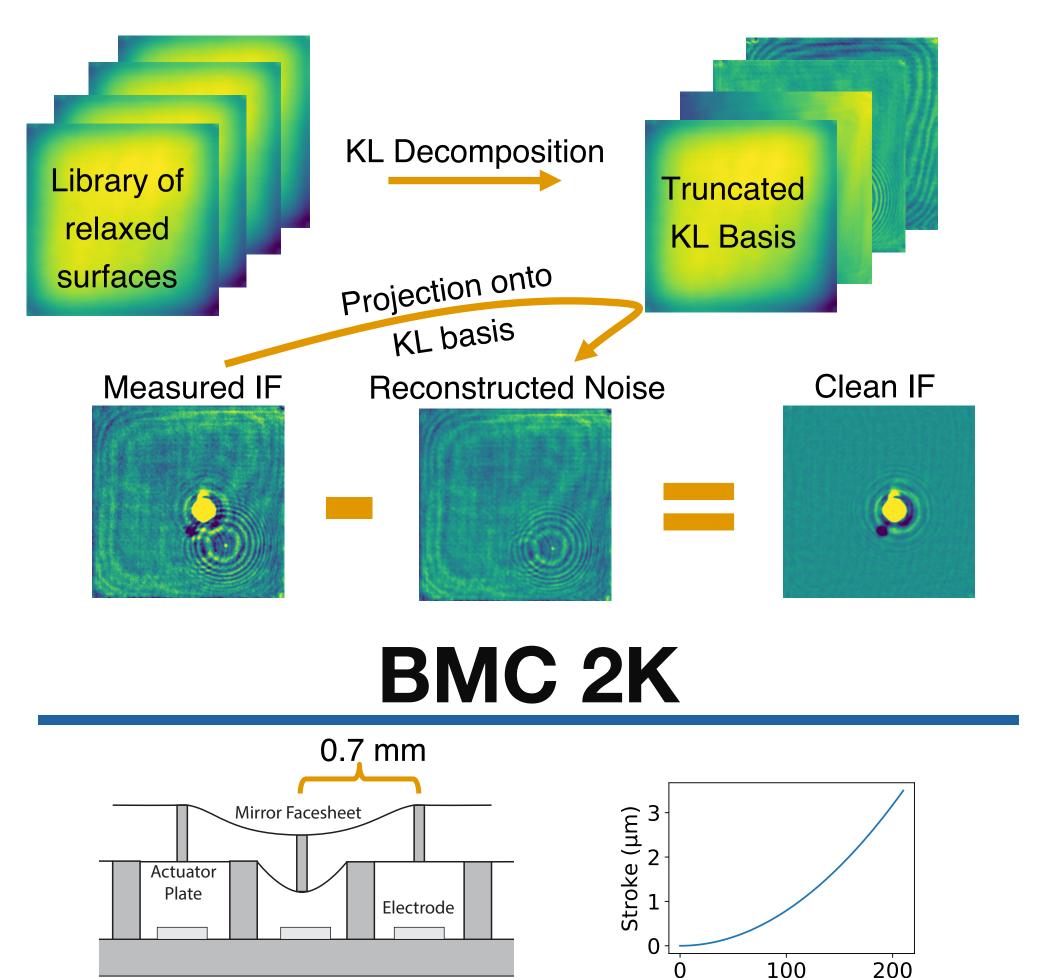


MagAO-X is an upgrade of the AO system on the Magellan Clay 6.5m telescope that will introduce extreme adaptive optics capabilities for high-contrast imaging at visible and near-infrared wavelengths. The upgrade features 3 deformable mirrors (DMs):

- One BMC 2K: 2040-actuator, 3.5µm stroke DM for high-order wavefront control
- Two ALPAO DM97-15s: 97-actuator, high-stroke DMs for low-order correction and non-commonpath (NCP) wavefront control in the coronagraph arm
- The accuracy of the wavefront correction is limited by our ability to precisely control the DMs, which requires careful characterization.

## **Characterization Pipeline**

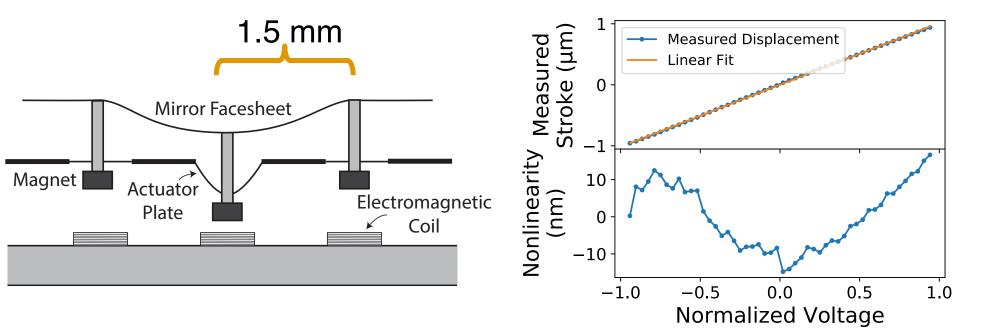
measured IF with Karhunen-Loève Image Projection (KLIP).



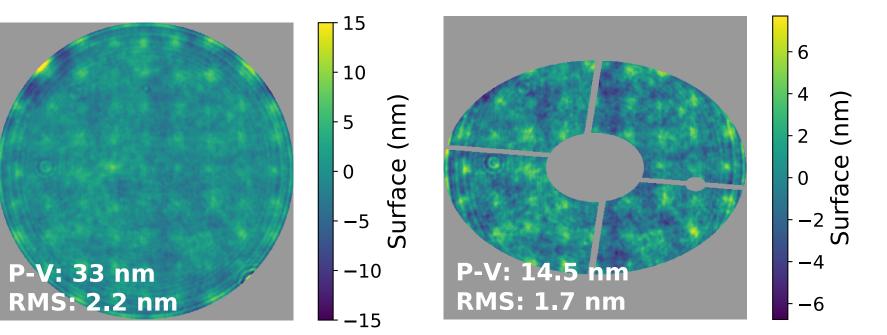
# • The 50x50 2K DM from Boston Micromachines Corporation (BMC) deforms a continuous facesheet via an electrostatic

Voltage (V)

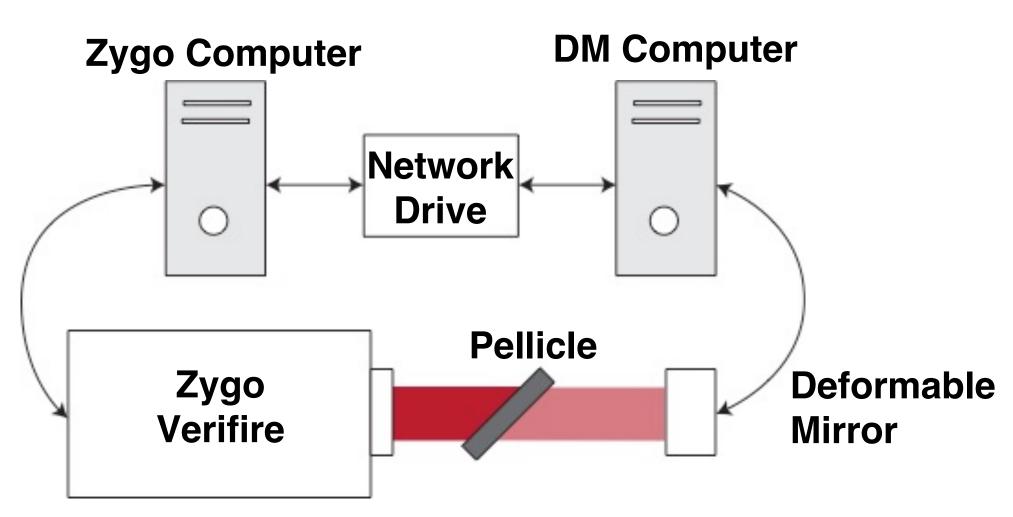
#### ALPAO DM97



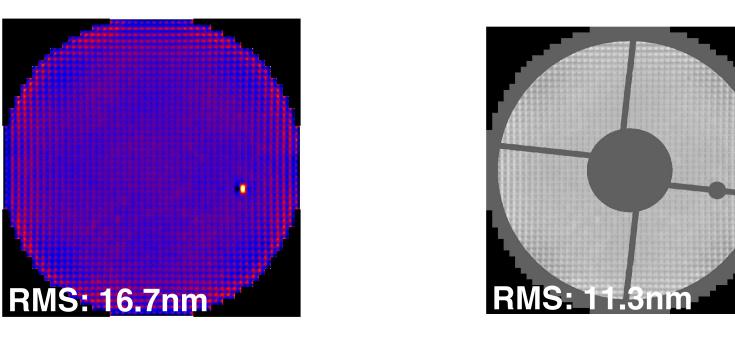
 The ALPAO DM97 actuates via an electromagnetic coil and permanent magnet mounted by post to a reflective facesheet, resulting in a linear voltagestroke relationship over a wide range of strokes.



 Following our characterization process, we achieved a flat of 2.2nm RMS over the full 13.5mm diameter and 1.7nm RMS over the MagAO-X pupil projected



In our testbed, we measure each DM surface with a Zygo Verifire (Fizeau) interferometer. Zygo data acquisition and DM control is automated and synchronized in Python. force between an electrode and actuator plate, resulting in an approximately quadratic voltage-stroke relationship.



- BMC's characterization of the 2K DM found one significant defect and a 16.7nm RMS flat over the 19.6mm diameter.
  Over the MagAO-X coronagraph pupil with the defect masked, the surface RMS reduces to 11.3nm.
- We expect to take delivery of the 2K during summer 2018.

onto the NCP DM in the coronagraph arm.

#### **Future Work**

- Inter-actuator coupling introduces a nonlinear stroke response, which leads to errors in the conventional control scheme. Modeling efforts are underway to develop an approach that accounts for this effect.
- Surface metrology will be improved by use of a high-reflectance Zygo reference flat and removal of the pellicle from the optical path.
- We will perform in-house characterization of the BMC 2K and a 2<sup>nd</sup> ALPAO DM97 upon delivery.

#### Acknowledgements

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#### THE UNIVERSITY OF ARIZONA College of Optical Sciences

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- 2. Blain 2012, Modelling MEMS Deformable Mirrors for Astronomical Optics
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- 4. Soummer et al 2012, *ApJL 755 L28*